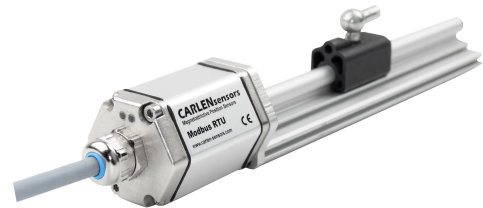


Magnetostrictive Linear Position Sensors Model series CHM/CPM with SSI - interface

- **Model CPM: Profile version**
- **Model CHM: Rod version**
- **Measuring strokes from 25 to 7600 mm**
- **Contactless, robust system**
- **Resolution up to 1 μ m**
- **Linearity < 0.01%**
- **Protection types up to IP 68**
- **Operating temperature range -40°C ... +85°C**
- **Rod version pressure stability up to 350 bar**
- **Cable : PUR or P VC**



Structure and operation

The displacement transducers operate according to the principle of run time measurement between two points of a magnetostrictive waveguide. One point is determined by a moveable position magnet, whose distance from the null point corresponds to the section to be measured. The run time of an emitted impulse is directly proportionate to this section. Conversion to a digital measuring signal takes place in the downstream electronics.

The waveguide is housed in a pressure-resistant stainless steel tube or extruded profile. To the rear of this is a die-cast aluminium housing containing the electronics in SMD technology. Electrical connection is implemented via a circular connector.

In the rod version, the position magnet is located in a ring, which is guided over the rod without contact. In the profile version, it is located either in a slider, which is linked to the moving part of the machine via a ball joint, or it moves as a liftable position magnet, without wear, over the profile.

Standard measuring strokes:

- ☐ Up to 1000 mm in 50 mm steps
- ☐ Up to 5000 mm in 250 mm steps (profile version: CPM)
- ☐ Up to 7600 mm in 250 mm steps (rod version: CHM)

Programming ex work

The displacement transducer is set to its ordered variables in the factory, as follows:

- ☐ Data length
- ☐ Data format
- ☐ Resolution (ref. to order code format)
- ☐ Measuring direction (ref. to order code format)
- ☐ Position value for start of measurement
- ☐ Alarm value for error (magnet removed)
- ☐ Differential measurement
- ☐ Speed value instead of position

Diagnose

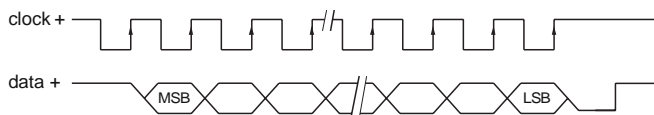
The LEDs (green/red) in the sensor head are used for adjustment and additionally provide information on the sensor status.

Green	Red	Meaning
On	Off	Normal function
On	On	Magnet not detected
On	Flashing	Sensor not synchronous *
Flashing	On	Setting mode

* Synchronous measurement only

SSI-profile

Impuls diagram



Clock sequence



Technical data

- Supply voltage range V_s : 24VDC (+20 / -15%) (polarity reversal protection)
- Supply current I_s : 100 mA typical
- Resolution: Max. 1 μ m
- Linearity: $\pm 0.01\%$ (min. $\pm 40 \mu$ m) with internal linearisation optionally up to 6 μ m
- Repeatability: $\pm 0.001\%$ (min. $\pm 1.0 \mu$ m)
- Hysteresis: $< 4 \mu$ m
- Measuring frequency: 500 to 3700 Hz depending on measuring length
- Temperature drift: < 15 ppm / $^{\circ}$ C
- Operating temperature range: - 40 $^{\circ}$ C to + 85 $^{\circ}$ C
- Dew point, humidity: 90 % rd. humidity, no condensation
- Shock test: 100 g to IEC Standard 68-2-27
- Vibration test: 15 g / 10 to 2000 Hz to IEC Standard 68-2-6
- Operating pressure for rod: 350 bar (optional 800 bar)
- Protection type:
 - Profile: IP 65
 - Rod: IP 67, IP 68 for cable outlet
- EMC test: EN 50081-1, EN 50081-2, EN 61000-4-2/3/4/6

SSI output

- Output: Differential signal to RS422 / 485
- Data length: 24bit / 25bit / 26bit (others on request)
- Coding: Binary / Gray
- Monoflop time: Max. 16 μ s
- Baudrate: Max. 1.0 Mbaud

Cable	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m
Baud rate	1,0 MBd	<400 kBd	<300 kBd	<200 kBd	<100 kBd

Mating connector:

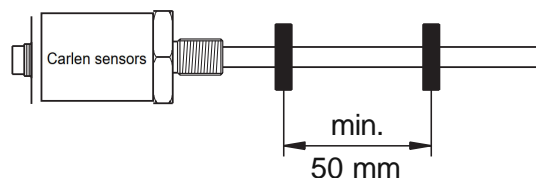
- Connection type: 7-pin connector M16
- Housing: Die-cast zinc, nickel-plated (straight or angled 90 $^{\circ}$)
- Contacts: Socket, Ag
- Cable strain relief: Pg 7
- Max. cable diameter: 6 mm
- Protection type: IP 67

Cable outlet:

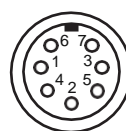
- Cable type: PUR cable 7 x 0.14 mm 2 with screen
- Bending radius: Min. 50 mm if routed firmly

Differentiation measurement

As an option the CPM / CHM transducer can give the difference of two positions. Thereby it has to be taken in consideration that the minimum distance between the two positions is 50 mm. In the range of a distance of 50 - 75 mm the linearity is double.



Electrical connections



Soldered connection side of connector

Pin	Wire	Signal
1	grey	Daten -
2	pink	Daten +
3	yellow	Clock +
4	green	Clock -
5	brown	+ VS (+ 24 VDC)
6	white	- VS (0 VDC)
7	Do not connect	

Order code format

■ Displacement transducer

CHM M / 1000 S 010 - 1 G 01

Electrical and
mechanical variants*

Code: G = Gray, B = Binary

No. of magnets (SSI: max.1)

Resolution in µm:
1, 2, 5, 10, 20, 50 or 100

Measuring direction

S = Positively ascending on move-
ment from the flange towards rod end
N = Descending on movement from
the flange towards rod end

Measuring stroke in mm

Design

CHM (rod):

M = With threaded connection
M 18 x 1.5

S = With threaded connection
16 UNF 3/4 "

CPM (profile):

1 = Position slider central ball joint
2 = Position slider front ball joint
3 = Lifiable position magnet

Model:

CPM = Profile version
CHM = Rod version

Scope of delivery:

Rod: Sensor, nut (order position magnet separately)

Profile: Sensor, 1 position magnet, 2 mounting clamps up
to 1250 mm + 1 clamp for each additional 500 mm.

Accessories:

■ Position magnets for CHM

CPR02 Standard position ring (ø 33 mm)

CPR03 Lifiable position magnet

CPR04 Position ring up to 100 °C (ø 25.4 mm)

■ Position magnets for CPM

CPS01 Position slider, central ball joint

CPS02 Position slider, front ball joint

CPR03 Lifiable position magnet

■ Available position magnets data sheet 11469

■ Mating connector (order separately)

CSTK7GS45 Straight

CSTK7WS46 Angled 90°

■ Installation material

CMB-MP-01 Mounting clamps for profile version

CNT-MP-01 M5 sliding block for profile version

Cable outlet on request

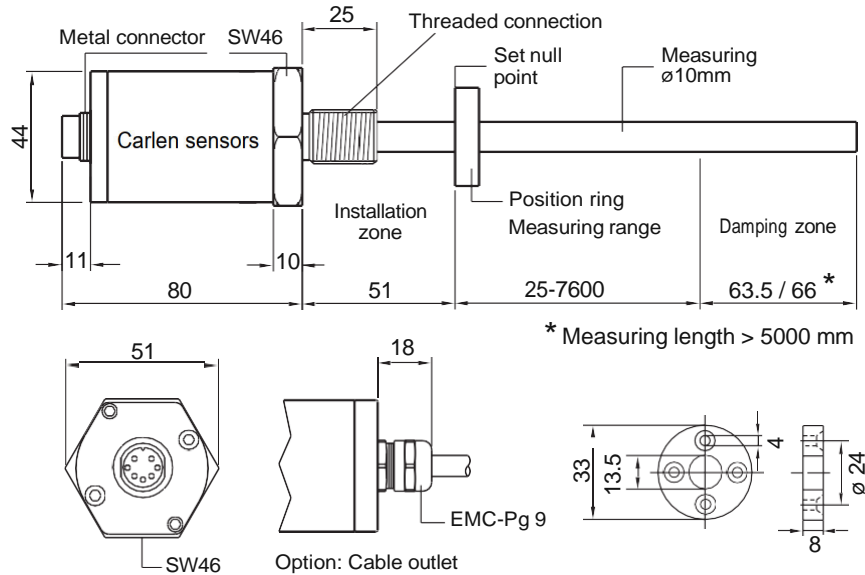
* The basic versions according to the data sheet bear the
number 01. Deviations are identified with a variant number and
are documented in the factory.

Dimensions in mm

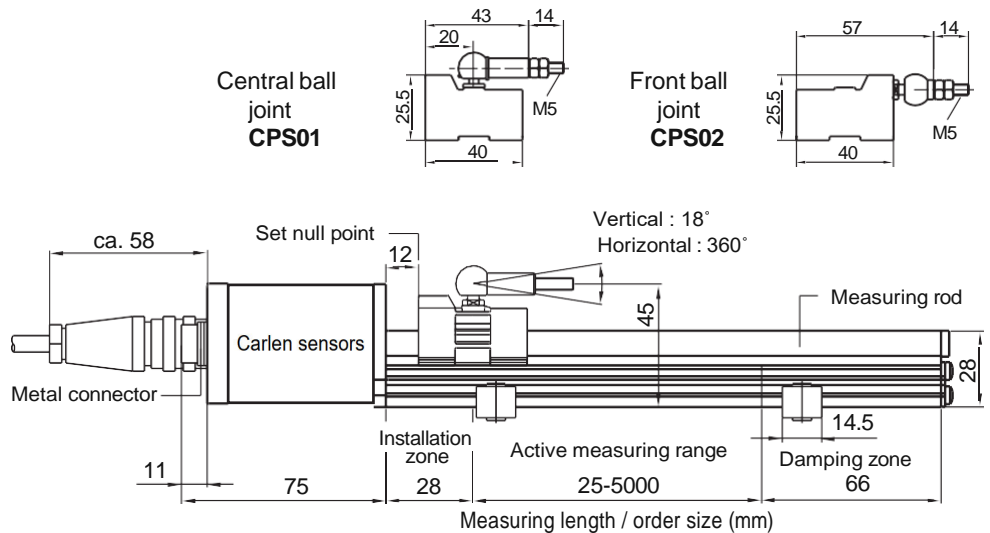
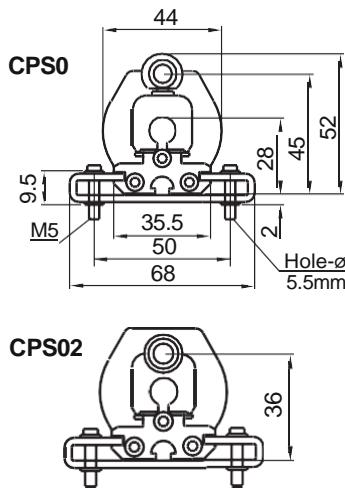
Model: CHM (rod version)

With measuring strokes of 1000 mm and over, mechanical rod support is recommended.

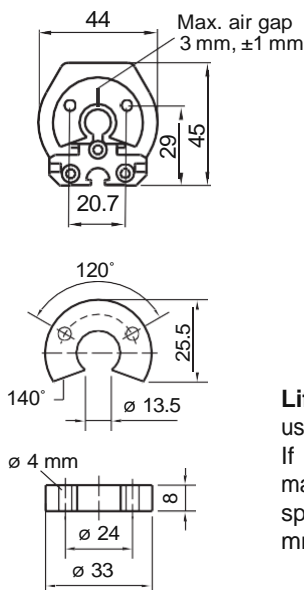
The sensor's fastening should be manufactured from non-magnetic materials (e.g.: brass, plastic). Note installation instruction **MWA10318** on installation in magnetisable materials.



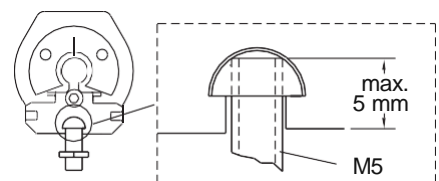
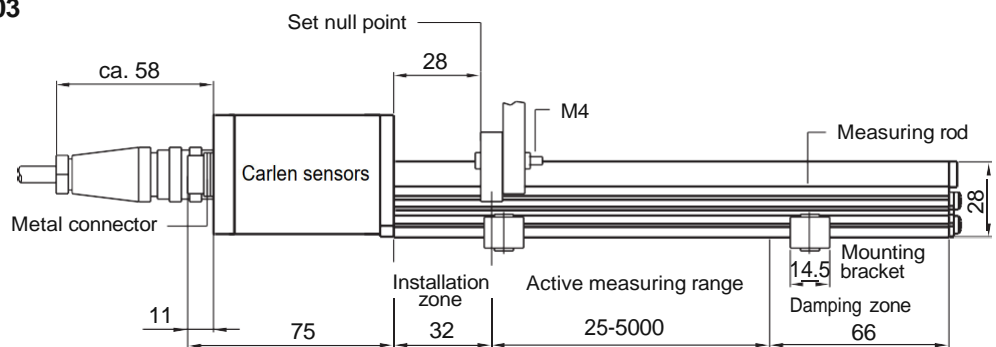
Model: CPM (profile version)



Liftable position magnet CPR03



Liftable position magnet Wherever possible, use non-magnetisable material for fastening this. If magnetisable material is used, the position magnet must be mounted via a non-magnetisable spacer washer with a minimum thickness of 5 mm using non-magnetisable bolts.



Sliding block: Studded nut in T slot

Note: On installation of the CARLENSensors, careful shielding from magnetic and electromagnetic fields must be ensured. The cable shield must be mounted on the connector and connected to ground at the evaluation electronics.